

- To estimate $\text{Var}(\bar{x} \cdot \bar{Y}) = \left(\sum_{i=1}^t \frac{\lambda_i^2}{r_i} \right) \hat{\sigma}^2$ unknown parameter
 $\bar{x} \cdot \bar{Y} \Leftrightarrow$
Note that $\text{MS(residual)} \stackrel{\text{!!!}}{\hat{\sigma}^2}$ is an unbiased est'or of σ^2
 $\therefore \left(\sum_{i=1}^t \frac{\lambda_i^2}{r_i} \right) \hat{\sigma}^2$ is an unbiased est'or of $\text{Var}(x \cdot Y)$

Def: ① standard error of $\sum \lambda_i \hat{\tau}_i$ ($\rightarrow \sum \lambda_i \tau_i$) is

$$\sqrt{\sum \frac{\lambda_i^2}{r_i}} \cdot \hat{\sigma}$$

② the std. error for $\hat{\tau}_i$ is $\hat{\sigma} / \sqrt{r_i}$, which is referred to as the std. error of a mean, and is abbreviated as S.E.M

③ the std. error of $\hat{\tau}_i - \hat{\tau}_j$ is

$$\sqrt{\frac{1}{r_i} + \frac{1}{r_j}} \cdot \hat{\sigma}$$

called std. error of a difference, abbreviated as S.E.D.

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Theorem 2.6 Suppose that the distribution of \mathbf{Y} is multivariate normal, that $\mathbb{E}(\mathbf{Y}) = \boldsymbol{\tau} \in V_T$ and that $\text{Cov}(\mathbf{Y})$ is a scalar matrix. Then the following hold.

(i) If $\mathbf{x} = \sum_{i=1}^t (\lambda_i / r_i) \mathbf{u}_i$ then

$$\frac{\mathbf{x} \cdot \mathbf{Y} - \sum \lambda_i \tau_i}{\sqrt{\left(\sum \frac{\lambda_i^2}{r_i} \right) \times \text{MS(residual)}} \stackrel{\text{!!!}}{\hat{\sigma}^2}}$$

↑ add this for test

has a t-distribution on $N - t$ degrees of freedom.

(ii) If \mathbf{x} and \mathbf{z} are in V and $\mathbf{x} \cdot \mathbf{z} = 0$ then $\mathbf{x} \cdot \mathbf{Y}$ and $\mathbf{z} \cdot \mathbf{Y}$ are independent estimators.

(Bailey) Sec.2.9. replication (r_1, \dots, r_t)

- Assume that all estimates of simple treatment differences are equally important. $\Rightarrow \text{Var}(\hat{\tau}_i - \hat{\tau}_j) = \hat{\sigma}^2 \left(\frac{1}{r_i} + \frac{1}{r_j} \right) \stackrel{\text{!!!}}{\hat{\sigma}^2} \rightarrow \hat{\tau}_i - \hat{\tau}_j$
- average variance of these est'ors:

$$\frac{1}{2} \sum_{i \neq j} \text{Var}(\hat{\tau}_i - \hat{\tau}_j) \quad \text{Note: no parameter in it.}$$

$$\frac{1}{t(t-1)} \sum_{i=1}^t \sum_{j \neq i} \left(\frac{1}{r_i} + \frac{1}{r_j} \right) = \frac{1}{t} \sum_{i=1}^t \frac{1}{r_i}$$

Proposition 2.7 If positive numbers r_1, \dots, r_t have a fixed sum R then $\sum (1/r_i)$ is minimized when $r_1 = r_2 = \dots = r_t = \frac{R}{t}$. \rightarrow may not be an integer

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Recall: Thm 2.5(i) BLUE for $x \cdot \tau$ is $x \cdot \underline{Y}$

e.g. A, B: two treatments.

$$\overline{C_A} \quad \overline{C_B}$$

Diagram illustrating two separate linear regression models for data points T_A and T_B :

Top model: $E(Y) = \beta_0 + \beta_1 T_A$ with coefficients r_A and r_B . The error term is U_A .

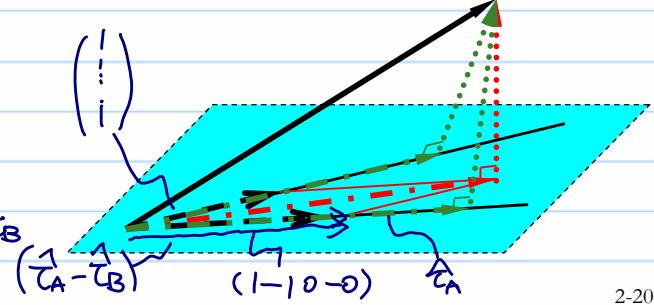
Bottom model: $E(Y) = \beta_0 + \beta_1 T_B$ with coefficients r_B and r_A . The error term is U_B .

Both models lead to the same BLUE estimate:

$$\hat{\beta} = (X'X)^{-1}X'Y = \begin{bmatrix} r_B & 0 \\ 0 & r_A \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 1 & -1 \\ 1 & -1 & 0 & 0 \end{bmatrix} \begin{bmatrix} y \end{bmatrix}$$

$$= \begin{bmatrix} \text{SUM}_{T=B}/r_B \\ \text{SUM}_{T=A}/r_A \end{bmatrix} = \begin{bmatrix} \hat{\beta}_B \\ \hat{\beta}_A \end{bmatrix}$$

Red circle highlights $\hat{\beta}_A$ with the note "different est'ors WHY?"



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(Bailey) Sec 2.10. Allowing for the overall mean

• 9m LNp.2-16,

$$\text{From LNp.2-16, } \text{EMS}(\bar{V}_T) = E\left(\frac{\|R_T(Y)\|^2}{\dim(V_T)}\right) = \frac{\sum_{i=1}^t r_i \bar{v}_i^2}{t} + \frac{\bar{v}_0^2}{t} = \text{EMS(residual)}$$

$$(*) \therefore \text{EMS}(T_T) - \text{EMS}(\text{residual}) = \frac{\sum_{i=1}^t r_i^2 T_i^2}{T} \geq 0$$

$(*) = 0$ if and only if $\tau_1 = \tau_2 = \dots = \tau_t = 0$

→ usually do not measure on a scale that make this plausible

- However, it is often plausible that $\tau_1 = \tau_2 = \dots = \tau_t$,

i.e. $E(Y_w) = k$ for all $w \in \mathbb{Z}$
 \rightarrow an unknown constant (parameter)
 $= k Y_0 \rightarrow [1]$

the model is called null model

- Let V_0 be the subspace of V which consists of scalar multiples of u_0 $\Rightarrow \dim(V_0) = 1$
 $\Rightarrow \{u_0\}$ is a basis of V_0 .

• By Thm 2.3 (III) (LNp.2-9)

Proposition 2.8 If $\mathbf{v} \in V$ then

$$P_{V_0}\mathbf{v} = \left(\frac{\mathbf{v} \cdot \mathbf{u}_0}{\mathbf{u}_0 \cdot \mathbf{u}_0} \right) \mathbf{u}_0 = \left(\frac{\text{grand total of } \mathbf{v}}{N} \right) \mathbf{u}_0 = \bar{v}\mathbf{u}_0 \quad \text{and} \quad \|P_{V_0}\mathbf{v}\|^2 = \left(\frac{\text{grand total of } \mathbf{v}}{N} \right)^2 \mathbf{u}_0 \cdot \mathbf{u}_0$$

$r_i \left\{ \begin{bmatrix} 1 \\ \vdots \\ 0 \\ 0 \end{bmatrix} \right\}$

$$= \frac{(\text{grand total of } \mathbf{v})^2}{N}$$

$$= N\bar{v}^2. \quad (\# \text{ of plots})$$

• $\mathbf{u}_0 = \mathbf{u}_1 + \dots + \mathbf{u}_t \in V_T \Rightarrow V_0 \subset V_T$ (Recall: $V = V_I \oplus V_T$)

↑ w.r.t. treatment

We can define

$\mathbf{v} \in W_T$
 $\mathbf{v} \cdot \mathbf{u}_0 = \bar{v} + \dots + \bar{v}_N$

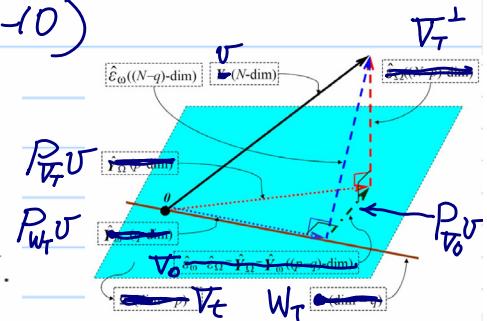
$\uparrow \bar{v}$ and find that (by Thm 2.3, LNp.2-10)

$$W_T = \{ \mathbf{v} \in V_T \mid \mathbf{v} \text{ is orthogonal to } V_0 \} = V_T \cap V_0^\perp$$

treatment contrast (i) $\dim W_T = \dim V_T - \dim V_0 = t - 1$;

(ii) $P_{W_T}\mathbf{v} = P_{V_T}\mathbf{v} - P_{V_0}\mathbf{v}$ for all \mathbf{v} in V ;

(iii) $\|P_{W_T}\mathbf{v}\|^2 + \|P_{V_0}\mathbf{v}\|^2 = \|P_{V_T}\mathbf{v}\|^2$ for all \mathbf{v} in V .



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• Applying (ii) and (iii) with $\mathbf{v} = \tau$ gives

$\begin{bmatrix} \tau_1 \\ \tau_2 \\ \vdots \\ \tau_t \end{bmatrix} = \sum_{i=1}^t \tau_i \cdot \mathbf{u}_i \in V_T$

$P_{W_T}\tau = \tau - P_{V_0}\tau = \tau - \bar{\tau}\mathbf{u}_0 = \sum_{i=1}^t (\tau_i - \bar{\tau})\mathbf{u}_i$

$\sum_{i=1}^t r_i(\tau_i - \bar{\tau})^2 = \|P_{W_T}\tau\|^2 = \|\tau\|^2 - \|\bar{\tau}\mathbf{u}_0\|^2 = \sum_{i=1}^t r_i\tau_i^2 - N\bar{\tau}^2$

$\because \mathbf{u}_i \text{ is a basis of } V_T$

which is zero if and only if all the τ_i are equal.

• Do not know τ : contain information of τ

Applying (ii) with $\mathbf{v} = \mathbf{y}$ gives

$$\begin{aligned} P_{W_T}\mathbf{y} &= \sum_{i=1}^t \left(\frac{\sum_{T=i}}{r_i} \right) \mathbf{u}_i - \frac{\sum}{N} \mathbf{u}_0 \\ &= \text{fitted values for treatments} - \text{fit for null model} \\ &= \sum_{i=1}^t (\hat{\tau}_i - \bar{y}) \mathbf{u}_i. \end{aligned}$$

c.f.

know $\hat{\tau}_1 - \bar{y}, \hat{\tau}_2 - \bar{y}, \dots, \hat{\tau}_t - \bar{y} \Rightarrow$ do not know $\hat{\tau}_1, \hat{\tau}_2, \dots, \hat{\tau}_t$

The coefficients $\hat{\tau}_i - \bar{y}$ are called treatment effects. Taking sums of squares gives

$$\begin{aligned} \sum_{i=1}^t r_i \hat{\tau}_i^2 &\leftarrow \|P_{W_T}\mathbf{y}\|^2 = \sum_{i=1}^t \frac{\sum_{T=i}^2}{r_i} - \frac{\sum^2}{N} = N\bar{y}^2. \end{aligned}$$

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Def: (Recall: LNp.2-14, c.f. LNp.2-16)

- sum of square for W_T : called SS for treatments abbreviated as SS(treatment)

$$MS(\text{treatment}) = \frac{SS(\text{treatment})}{\dim(W_T) = t-1}$$

- SS for V_0 : called (crude) SS for mean abbreviated as SS(mean)

$$MS(\text{mean}) = \frac{SS(\text{mean})}{\dim(V_0) = 1}$$

- $SS(\text{treatment}) = \text{crude SS for treatment } (\|P_{V_T} y\|^2) - SS(\text{mean})$

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(Bailey) 2.11. hypothesis testing.

According to "treatment structure", we split

$$V = V_T \oplus V_T^\perp$$

↑ residual

$$V = V_0 \oplus W_T \oplus V_T^\perp$$

$$\text{dimension } N = 1 + (t-1) + (N-t)$$

$$\text{data } y = \underbrace{\bar{y}u_0}_{\substack{\text{overall mean} \\ \|P_{V_0} y\|^2}} + \underbrace{\left(\sum_i \text{mean}_{T=i} u_i - \bar{y}u_0 \right)}_{\substack{\text{treatment effects} \\ \|P_{W_T} y\|^2}} + \underbrace{\left(y - \sum_i \text{mean}_{T=i} u_i \right)}_{\substack{\text{residual} \\ \|P_{V_T^\perp} y\|^2}}$$

$$\text{sum of squares } \sum_{\omega \in \Omega} Y_{\omega}^2 = \underbrace{\frac{\text{SUM}^2}{N}}_{\|P_{V_0} y\|^2} + \underbrace{\frac{SS(\text{treatments})}{\|P_{W_T} y\|^2}}_{\frac{\text{SUM}^2}{t-1}} + \underbrace{\frac{SS(\text{residual})}{\|P_{V_T^\perp} y\|^2}}_{\frac{SS(\text{residual})}{N-t}}$$

mean square

$= SS / \dim(\cdot)$ d.f.

$$\text{expected mean square} = E \left(\frac{\|P_{W_T} y\|^2}{\dim(\cdot)} \right) N\bar{\tau}^2 + \sigma^2 \quad \frac{\sum_i r_i \tau_i^2 - N\bar{\tau}^2}{t-1} + \sigma^2 \quad \sigma^2$$

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- Test $H_0: \bar{\tau} = 0$ against $H_1: \bar{\tau} \neq 0$

$$V = V_0 \oplus W_T \oplus V_T^\perp$$

expected mean square under H_0 $\underbrace{N\bar{\tau}^2 + \sigma^2}_{\parallel \sigma^2}$ $\underbrace{\frac{\sum_i r_i \tau_i^2 - N\bar{\tau}^2}{t-1} + \sigma^2}_{\parallel \sigma^2}$ $\underbrace{\sigma^2}_{\parallel \sigma^2}$

$$\text{MS(mean)} \approx \text{MS(residual)} \Rightarrow \frac{\text{MS(mean)}}{\text{MS(residual)}} \begin{cases} \text{small} \rightarrow H_0 \\ \text{large} \rightarrow H_1 \end{cases}$$

under H_1 \gg

- $H_0: \tau_1 = \dots = \tau_t \equiv \bar{\tau}$ against $H_1: \text{at least one not equal}$

$$V = V_0 \oplus W_T \oplus V_T^\perp$$

expected mean square under H_0 $N\bar{\tau}^2 + \sigma^2$ $\underbrace{\frac{\sum_i r_i \tau_i^2 - N\bar{\tau}^2}{t-1} + \sigma^2}_{\parallel \sigma^2}$ σ^2

$$\text{MS(treatment)} \approx \text{MS(residual)} \Rightarrow \frac{\text{MS(treatment)}}{\text{MS(residual)}} \begin{cases} \text{small} \rightarrow H_0 \\ \text{large} \rightarrow H_1 \end{cases}$$

under H_1 \gg

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• ANOVA table

↳ interested in the comparison of treatment means (i.e., τ_i 's)

source	sum of squares	degrees of freedom	mean square	variance ratio
mean	$\frac{\text{sum}^2}{N}$	1	SS(mean)	$\frac{\text{MS(mean)}}{\text{MS(residual)}}$
treatments	$\sum_i \frac{\text{sum}_{T=i}^2}{r_i} - \frac{\text{sum}^2}{N}$	$t-1$	$\frac{\text{SS(treatments)}}{t-1}$	$\frac{\text{MS(treatments)}}{\text{MS(residual)}}$
residual	← by subtraction →		$\frac{\text{SS(residual)}}{\text{df(residual)}}$	
Total	$\sum_{\omega} y_{\omega}^2$	N		

$$\sum_{\omega} (y_{\omega} - \bar{y})^2$$

$$V = V_0 \oplus W_T \oplus V_T^\perp$$

$$V_0^\perp = W_T \oplus V_T^\perp$$

under H_0
 $F_{t-1, N-t}$

Theorem 2.9 Suppose that the distribution of \mathbf{Y} is multivariate normal. Let W_1 and W_2 be subspaces of V with dimensions d_1 and d_2 . Then the following hold.

- If $P_{W_1}\tau = \mathbf{0}$ then $\text{SS}(W_1)/\sigma^2$ has a χ^2 -distribution with d_1 degrees of freedom.
- If W_1 is orthogonal to W_2 and $P_{W_1}\tau = P_{W_2}\tau = \mathbf{0}$ then $\text{MS}(W_1)/\text{MS}(W_2)$ has an F-distribution with d_1 and d_2 degrees of freedom.

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$\mathbb{H}_0(\tau_1, \dots, \tau_T) \in \mathbb{R}^T$	$\mathbb{E}(Y_\omega) = \tau_{T(\omega)}$	$\mathbb{E}(\mathbf{Y}) \in V_T$	V_T	$\left. \cup \right\} W_T$
	add assumption $\tau_1 = \tau_2 = \dots = \tau_T$		V_0	
$\mathbb{H}_0(\tau_1, \dots, \tau_T) \in \mathbb{R}^T$	$\mathbb{E}(Y_\omega) = \kappa$	$\mathbb{E}(\mathbf{Y}) \in V_0$	V_0	$\left. \cup \right\} V_0$
$\mathbb{H}_0(\tau_1, \dots, \tau_T) \in \mathbb{R}^T$	add assumption $\tau_1 = 0$		$\{0\}$	
$(\tau_1, \dots, \tau_T) \in \mathbb{R}^T$	$\mathbb{E}(Y_\omega) = 0$	$\mathbb{E}(\mathbf{Y}) \in \{0\}$	$\{0\}$	

Sec 2.12. Sufficient replication for power
(reading assignment)