

# 多階層實驗設計期末報告

## $L^k$ Fractional Experiment With Hard-To Change and Easy-To-Change Factors

學號：9524513  
學生：林侑廷

### Five different run order scenarios

- Completely randomized
- RRO
- Completely restricted
- Partially restricted
- Classical split-plot procedure

### What is hard-to-change factor

改變因子狀需要耗掉許多時間或耗大比  
經費不符合經濟成本

此報告中  $X_1$  代表hard-to-change 因子

例如：改變鍋爐狀態 或者 紙漿的問題

### Completely randomized

完全的隨機排列

例如

二因子二水平的設計共有四階層的排列方  
式

## RRO

Random run order with the hard-to-change factor is not reset successive runs have the same level of that factor

例子

$X_1$  is reset at runs  
1,3,6,8

TABLE 1. A Run Order for a  $2^3$  Experiment

run	$X_1$	$X_2$	$X_3$	Block
1	-	+	-	1
2	-	-	+	1
3				2
4	-	+	+	2
5		+		2
6				3
7	-	+	+	3
8	-	-	+	4

## Partially restricted

The runs at each level of the hard-to-change factor are randomly divided into two groups of equal size or of sizes that differ by a run

## Completely restricted

Hard-to-change factor 各個level 出現在相同的 block 之中

## Covariance Matrix(V) for the Run Order Scenarios

$\mathcal{E}_s$  be the error of easy-to-change factor With a mean zero and a various  $\sigma_s^2$

$\mathcal{E}_w$  be the error of hard-to-change factor With a mean zero and a various  $\sigma_w^2$

## Covariance Matrix(V) for the Run Order Scenarios-續

$$V = (\sigma_S^2 + (1-p)\sigma_W^2)I + (p\sigma_W^2)U_r U_r^t$$

$p$  is the probability that any two runs having the same setting of the hard-to-change factor are in the same block

- For completely randomized

$$V_{cr} = (\sigma_S^2 + \sigma_W^2)\mathbf{I} = \sigma^2\mathbf{I}$$

because the whole-plot factor reset on each run

- For a completely restricted

$$V_r = \sigma_S^2\mathbf{I} + \sigma_W^2\mathbf{U}_r \mathbf{U}_r'$$

$$\mathbf{U}_r = \begin{bmatrix} \mathbf{J}_1 & & \\ & \vdots & \\ & & \mathbf{J}_L \end{bmatrix} \quad \mathbf{J}_i = [1, 1 \cdots 1]_{L^{k-1}}.$$

## Covariance Matrix(V) for the Run Order Scenarios-續

Completely restricted  $p=1$

Completely randomized  $p=0$

Partially restricted

$$\text{--block is even } p = \frac{L^{k-1}-2}{2(L^{k-1}-1)}$$

$$\text{--block is odd } p = \frac{L^{k-1}-1}{2(L^{k-1})}$$

$$\text{RRO } p = \frac{2}{L^{k-1}(L-1)+2}$$

For a RRO design

the  $2^3$  experiment : 3,1,4,5,8,7,6,2

$$\begin{array}{c|ccc} \text{run} & X_1 & X_2 & X_3 \\ \hline 3 & - & + & - \\ 1 & - & - & - \\ 4 & - & + & - \\ 5 & + & - & - \\ 8 & + & - & - \\ 7 & + & - & - \\ 6 & - & - & - \\ 2 & - & - & - \end{array} \quad \mathbf{U} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

$$\begin{array}{c|ccc} \text{run} & X_1 & X_2 & X_3 \\ \hline 1 & - & - & - \\ 2 & - & - & 1 \\ 3 & - & - & - \\ 4 & - & - & 1 \\ 5 & + & - & - \\ 6 & + & - & 1 \\ 7 & + & - & - \\ 8 & + & - & 1 \end{array} \quad \mathbf{U} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix} \quad \mathbf{U}\mathbf{U}' = \begin{bmatrix} 1 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 \end{bmatrix}.$$

# $V(b_i)$ in the $L^k$ system

$$Y = X\beta + \varepsilon$$

For  $L^k$  experiment using different run order scenarios

$$\begin{aligned} Cov(\mathbf{b}) &= (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{V}\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1} \\ &= \sigma_S^2(\mathbf{X}'\mathbf{X})^{-1} \\ &\quad + \sigma_W^2(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'[(1-p)\mathbf{I} + p\mathbf{U}\mathbf{U}']\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1} \\ &= \sigma_S^2 f_1(\mathbf{X}) + \sigma_W^2 f_2(\mathbf{X}). \end{aligned}$$

Compare the variance of  $b_i$

$$V(b_i) = a_i \sigma_S^2 + c_i \sigma_W^2 \quad i = 0, 1, \dots,$$

## Completely randomized v.s. completely restricted

- In hard-to-change factor completely randomized is better
- In easy-to-change factor completely restricted is better
- About price completely restricted is better

## a and c value for $2^k$ experiment with $X_1$ Hard-To-Change

Factor	All Randomizations	General Formula	Completely Restricted	Partially Restricted	Random Run Order	Completely Randomized	Orthogonal Blocking
$i = 1$	$\frac{1}{2^k}$	$\frac{(i-1)}{2^{k-1}} + \frac{p}{2}$	$\frac{1}{2}$	$\frac{1}{4}$	$\frac{2}{(2^{k-1}+1)}$	$\frac{1}{2}$	$\frac{1}{2^k}$
$i \neq 1$	$\frac{1}{2^k}$	$\frac{(i-1)}{2^{k-1}}$	0	$\frac{1}{(2^{k-1}-1)}$	$\frac{1}{(2^{k-1}+1)}$	$\frac{1}{2^k}$	0

Example:  $2^3$  System With  $X_1$  Hard To Change

Run Order Scenario	$V(b_{i1})$	$V(b_{i2}) = V(b_{i3}) = \dots$
Completely Restricted	$\frac{1}{8}\sigma_W^2 + \frac{1}{16}\sigma_S^2$	$\frac{1}{16}\sigma_S^2$
Partially Restricted	$\frac{1}{2}\sigma_W^2 + \frac{1}{16}\sigma_S^2$	$\frac{1}{16}\sigma_W^2 + \frac{1}{16}\sigma_S^2$
Random Run Order	$\frac{5}{16}\sigma_W^2 + \frac{1}{16}\sigma_S^2$	$\frac{5}{16}\sigma_W^2 + \frac{1}{16}\sigma_S^2$
Completely Randomized	$\frac{1}{16}\sigma_W^2 + \frac{1}{16}\sigma_S^2$	$\frac{1}{16}\sigma_W^2 + \frac{1}{16}\sigma_S^2$
Orthogonal Blocking	$\frac{1}{16}\sigma_W^2 + \frac{1}{16}\sigma_S^2$	$\frac{1}{16}\sigma_S^2$

## Split plot v.s. partially restricted

- For the hard-to-change factor both has the same standard error (because they have four blocks)
- For all other factors split plot is better than partially restricted

## Classical Split Plot Blocking

Two different scheme

1. four blocks  $I = X_1 = X_1 X_2 X_3 X_4$
2. eight blocks  $I = X_1 = X_2 X_3 = X_1 X_2 X_4$

## $2^4$ G-efficiency

When costs and prediction variance are criteria, G-efficiency is important

Completely randomized  $2^4$  factorial is a G-optimum experiment

$11(\sigma_s^2 + \sigma_w^2)/16$  for a main effects plus interaction model

## For the four blocks scheme

X matrix is written in the standard order

$$\mathbf{U} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

## G-efficiency--(continued)

- Split –plot experiment with four blocks the maximum variance is  $\sigma_s^2/2 + 11\sigma_w^2/16$
- Split-plot design can be superior to “optimum” designs

## Concluding Remarks

- When errors are introduced by changing the level of the factors, RRO and completely randomized are not well for easy-to-change factor
- Restricted experiments are more economical but there is a large variance for the hard-to-change factor

## Concluding Remarks--(continued)

- Some people use partially restricted it is not good we can use Split plot blocking procedures