

Center Points and Curvature Check

→ 2-level factor → 3-level factor.

- Purposes of adding replicated center points to a 2-level first-order experiment
 - pure error estimate
 - using 2^{k-p} or OA

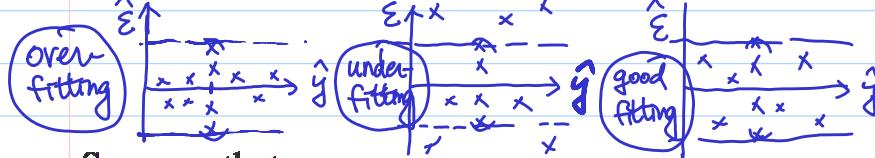
– it allows the check of the overall curvature effect,

Note constant variance assumption

$\hat{\sigma}^2$

– it provides an unbiased estimate of the process error variance

– it allows the over-fitting/under-fitting check in residual plot



can do t-test
for saturated
 2^{k-p}

- Suppose that

– the first-order experiment is based on a 2-level orthogonal design with run size n_f , and

i.e. resolution ≥ 3
strength ≥ 2

projection onto any 2 factors
→ full 2^2 design.

– n_c center point runs are added to the first-order experiment.

Center Points and Curvature Check

- Let $\bar{y}_f = \frac{\sum_{x \in D} y_x / n_f}{n_f}$ = sample average over factorial runs with level ± 1 ,

$\bar{y}_c = \frac{\sum_{x=0} y_x / n_c}{n_c}$ = sample average at n_c center points with level 0

- Under the second-order model

$$E\left(\frac{\sum_{x \in D} y_x}{n_f}\right) = \sum_{x \in D} E(y_x) / n_f$$

$$y_x = \beta_0 + \sum_{i=1}^k \beta_i x_i + \sum_{i < j} \beta_{ij} x_i x_j + \sum_{i=1}^k \beta_{ii} x_i^2 + \epsilon, \quad \epsilon \sim N(0, \sigma^2 I)$$

may be aliased

$$E(\bar{y}_c) = \beta_0, \quad \sum_{x \in D} x_i = 0, \sum_{x \in D} x_i x_j = 0, \sum_{x \in D} x_i^2 = n_f$$

$$E(\bar{y}_f) = \beta_0 + \sum_{i=1}^k \beta_{ii},$$

$$E(\bar{y}_f - \bar{y}_c) = \sum_{i=1}^k \beta_{ii}, \text{ and}$$

$$Var(\bar{y}_f - \bar{y}_c) = \sigma^2 \left(\frac{1}{n_f} + \frac{1}{n_c} \right).$$

$$y \sim \beta_0 + \{x_i \text{ s, } x_i x_j \text{ s estimable model}\} + \underbrace{(\beta_{11} + \dots + \beta_{kk})}_{\beta^*} x_i^2 + \epsilon$$

- overall curvature parameter: $\beta_{11} + \dots + \beta_{kk}$

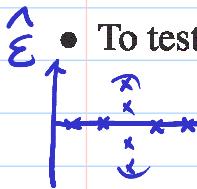
– In using the overall curvature to measure the curvature effects, it is possible that some of the large β_{ii} cancel each other, thus yielding a very small $\sum_{i=1}^k \beta_{ii}$.

LNP.3-29.

– This rarely occurs unless exp'tal region near a saddle point of the f .

Center Points and Curvature Check

- To test the hypotheses



$$H_0: \beta_{11} + \dots + \beta_{kk} = 0 \text{ v.s. } H_a: \beta_{11} + \dots + \beta_{kk} \neq 0$$

we can use $\bar{y}_f - \bar{y}_c$.

- Reject H_0 at level α if

Same as the $\hat{\sigma}^2$
under the LM in
LNp.3-10 if
 $\#\{B_0, B_i's, B_{ij}\} = n_f$

where $s^2 = \text{sample variance based on } n_c \text{ center runs is used to estimate } \sigma^2$.

$$\text{indep} \rightarrow \frac{|\bar{y}_f - \bar{y}_c|}{s \sqrt{\frac{1}{n_f} + \frac{1}{n_c}}} > t_{n_c-1, \frac{\alpha}{2}}$$

- If the curvature check is not significant the search may continue with the use of another first-order experiment and steepest ascent. Otherwise, it should be switched to a second-order experiment.

→ stay in the original exp'tal region.

orthogonal design

Center Points and Curvature Check

- Justification from regression analysis:

Design matrix

$$\begin{matrix} x_1 & x_k \\ \hline +1 & +1 \\ +1 & -1 \\ \vdots & \vdots \\ -1 & -1 \end{matrix}$$

n_f

n_c

$$\begin{matrix} 0 & \dots & 0 \\ 0 & \dots & 0 \end{matrix}$$

model matrix

$$\begin{matrix} \sum x_i = 0 & \sum x_i x_k = 0 & \sum x_i^2 = n_f \\ \hline \sum x_1 \dots x_k & x_1 x_2 \dots x_{k-1} x_k & x_1^2 \dots x_k^2 \\ \begin{matrix} +1 & +1 & \dots & +1 & -1 \\ +1 & -1 & \dots & -1 & +1 \\ \vdots & \vdots & \dots & \vdots & \vdots \\ -1 & -1 & \dots & +1 & -1 \\ 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & 0 \end{matrix} & \begin{matrix} +1 & -1 \\ 0 & 0 \end{matrix} & \begin{matrix} +1 & +1 & \dots & +1 & +1 \\ +1 & +1 & \dots & +1 & +1 \\ \vdots & \vdots & \dots & \vdots & \vdots \\ +1 & +1 & \dots & +1 & +1 \\ 0 & 0 & \dots & 0 & 0 \end{matrix} \end{matrix}$$

$x_f^T x_g$ is nonsingular

$$Y = X\beta + \epsilon$$

$$X = \begin{bmatrix} x_f & \sum x_i^2 & \sum x_i \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} \hat{\beta}_0 \\ \hat{\beta}^* \end{bmatrix} = (Z^T Z)^{-1} Z^T Y$$

$$(Z^T Z)^{-1} = \begin{bmatrix} 1/n_c & -1/n_c \\ -1/n_c & 1/(n_c n_f) \end{bmatrix}$$

$$(Z^T Z)^{-1} Z^T Y =$$

$$\begin{bmatrix} \sum y_x + \sum y_k \\ \sum x_i y_x \end{bmatrix}$$

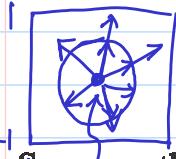
$$Z^T Z = \begin{bmatrix} n_c + n_f & n_f \\ n_f & n_f \end{bmatrix}$$

$$\frac{-1/n_c}{n_c + n_f / (n_c n_f)} \propto \text{Var}(\hat{\beta}^*)$$

Least square give same estimate of β^* , but t-tests could be different.

$$\begin{bmatrix} -\frac{\sum x_i y_k + \sum y_k^2}{n_c} + \left(\frac{1}{n_c} + \frac{1}{n_f}\right) \sum x_i y_x \\ \frac{\sum y_k}{n_f} - \frac{\sum y_k}{n_c} = \bar{y}_f - \bar{y}_c \end{bmatrix}$$

✓ Reading: textbook, 10.3.1



Steepest Ascent Search

- Suppose the fitted model is

 x_0

x_1, x_2 's not significant

x_i^2 's : : $\hat{y} = \hat{\beta}_0 + \sum_{i=1}^k \hat{\beta}_i x_i$

$\hat{x}_0 \rightarrow \hat{x}_0 + \Delta$, where $\|\Delta\|^2 = d$

Q: What Δ cause largest increase/decrease on \hat{y} under the model?

- Taking the partial derivative of \hat{y} with respect to x_i

$$\frac{\partial \hat{y}}{\partial x_i} = \hat{\beta}_i, \quad i = 1, \dots, k.$$

$$\max_{\Delta} \hat{y}(\hat{x}_0 + \Delta) - \hat{y}(\hat{x}_0) \\ = \sum \hat{\beta}_i \Delta_i.$$

subject to $\|\Delta\|^2 = d$

Lagrange method

- The steepest ascent direction (for maximization) is

$$\lambda \cdot (\hat{\beta}_1, \dots, \hat{\beta}_k), \quad \lambda > 0, \quad \Rightarrow \max_{\Delta} \sum \hat{\beta}_i \Delta_i + \lambda (\|\Delta\|^2 - d)$$

$$\lambda \cdot (\hat{\beta}_1, \dots, \hat{\beta}_k), \quad \lambda > 0, \quad \equiv t(\Delta, \lambda) \quad \Delta^2$$

and the steepest descent direction (for minimization) is $\frac{\partial t}{\partial \Delta_i} = \hat{\beta}_i + 2\lambda \Delta_i = 0$

$$\lambda \cdot (\hat{\beta}_1, \dots, \hat{\beta}_k), \quad \lambda < 0. \quad \Rightarrow \Delta_i \propto \hat{\beta}_i$$

Steepest Ascent Search

- The search for a higher (lower) response continues by
 - drawing a line from the center point of the design in the steepest ascent (descent) direction
 - performing several runs along the steepest ascent (descent) path
 - taking the location on the path where a maximum (minimum) response is observed as the center point for the next experiment
- The design for the next experiment is again a first-order design plus some center runs.

Note 1: the linear approximation (first-order fitted model) to the unknown true response is adequate in exp'tal region or region not far away the exp'tal region.

Note 2: What if we change coding of effects, can we still get similar/same result? \rightarrow RSM more interested in \hat{y} , not $\hat{\beta}$.

Illustrated Initial First-Order Experiment

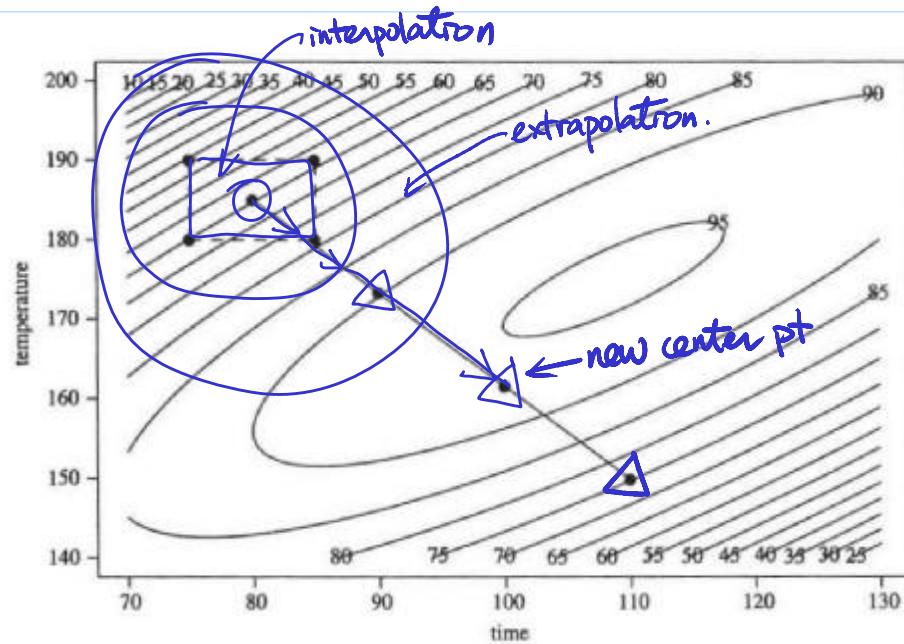


Figure 3: First-order experiment with steepest ascent

Illustrated Initial First-Order Experiment

Table 3: Design Matrix and Yield Data for First-Order Design

Run	Factor		Yield
	Time	Temperature	
1	-1 75min	180°C -1	65.60
2	-1 75min	190°C 1	45.59
3	1 85min	180°C -1	78.72
4	1 85min	190°C 1	62.96
5	0 80min	185°C 0	64.78
6	0 80min	185°C 0	64.33
7	2	2(-1.173) ²⁵	89.73
8	4	4(-1.173) ⁴²	93.04
9	6	6(-1.173)	75.06

2-level design + center pt.

2 level full factorial, can be used to estimate $\beta_0, \beta_1, \beta_2, \beta_1\beta_2$

1st order fitted model still work.

Illustrated Initial First-Order Experiment

- Model:

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_{12} x_1 x_2 + (\beta_{11} + \beta_{22}) x_1^2,$$

Table 4: Least Square Estimates, Standard Errors, t Statistics and p-values, Initial First-Order Experiment

1st-order model is OK. ↗

move to a new experimental region.

$n_f = 4$.
of $\{\beta_0, \beta_1, \beta_2, \beta_{12}\}$ = 4

$\sigma^2 = 5^2$

Effect	Standard				p-value
	Estimate	Error	t		
intercept	64.5550	0.2250	286.91	0.00	
β_1	7.6225	0.1591	47.91	0.01	
β_2	-8.9425	0.1591	-56.21	0.01	
β_{12}	1.0625	0.1591	6.68	0.09	not significant
$\beta_{11} + \beta_{22}$	-1.3375	0.2756	-4.85	0.13	L-curvature check.

Illustrated Steepest Ascent Search

- Steepest ascent direction: $(7.622, -8.942)$ or equivalently, $(1, -1.173)$
- Increasing time in steps of 2 units (10 minutes) is used because a step of 1 unit would give a point near the southeast corner of the first order design
- The results for three steps appear as runs 7-9 in Table 3.
- Because run 8 (time=4, temperature=4(-1.173)) correspond to the maximum yield along the path, they would be a good center point for the next experiment
- A first-order experiment can be run as indicated by runs 1-6 in Table 5.

Illustrated Steepest Ascent Search

Table 5: Design Matrix and Yield Data for Second-Order Design

Run	Factor		Yield
	Time	Temperature	
1	-1	-1	91.21
2	-1	1	94.17
3	1	-1	87.46
4	1	1	94.38
5	0	0	93.04
6	0	0	93.06
7	-1.41	0	93.56
8	1.41	0	91.17
9	0	-1.41	88.74
10	0	1.41	95.08

2-level design
+ center pts.

axial pts

$$x_1^2 = x_2^2$$

$$x_1^2 \neq x_2^2$$

Illustrated Second-Order Experiment

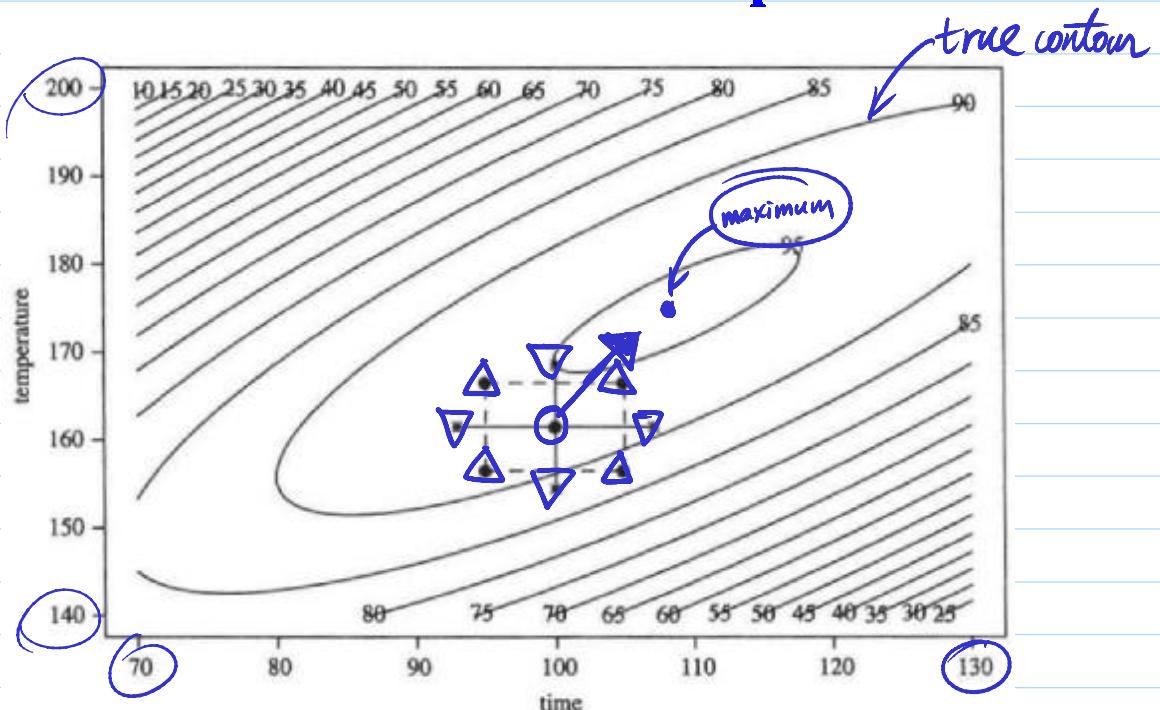


Figure 4: Second-order experiment

Illustrated Second-Order Experiment

Table 6: Least Square Estimates, Standard Errors, t Statistics and p-values for Follow-up

First-Order Experiment

*Fitting 1st-order
model is not
enough*

Effect	Estimate	Standard		
		Error	t	p-value
intercept	93.0500	0.0100	9305.00	0.000
β_1	-0.8850	0.0071	-125.17	0.005
β_2	2.4700	0.0071	349.31	0.002
β_{12}	0.9900	0.0071	140.01	0.005
$\beta_{11} + \beta_{22}$	-1.2450	0.0122	-101.65	0.006

CP. $\hat{\beta}_1$ & $\hat{\beta}_2$ in Table 4 (LNp.3-17)

*significant
curvature
check.*

Table 7: Least Square Estimates, Standard Errors, t Statistics and p-values for Second-Order Experiment

Effect	Estimate	Standard		
		Error	t	p-value
intercept	93.0500	0.2028	458.90	0.000
β_1	-0.8650	0.1014	-8.53	0.001
β_2	2.3558	0.1014	23.24	0.000
β_{12}	0.9900	0.1434	6.90	0.002
β_{11}	-0.4256	0.1341	-3.17	0.034
β_{22}	-0.6531	0.1341	-4.87	0.008

significant

Illustrated Second-Order Experiment

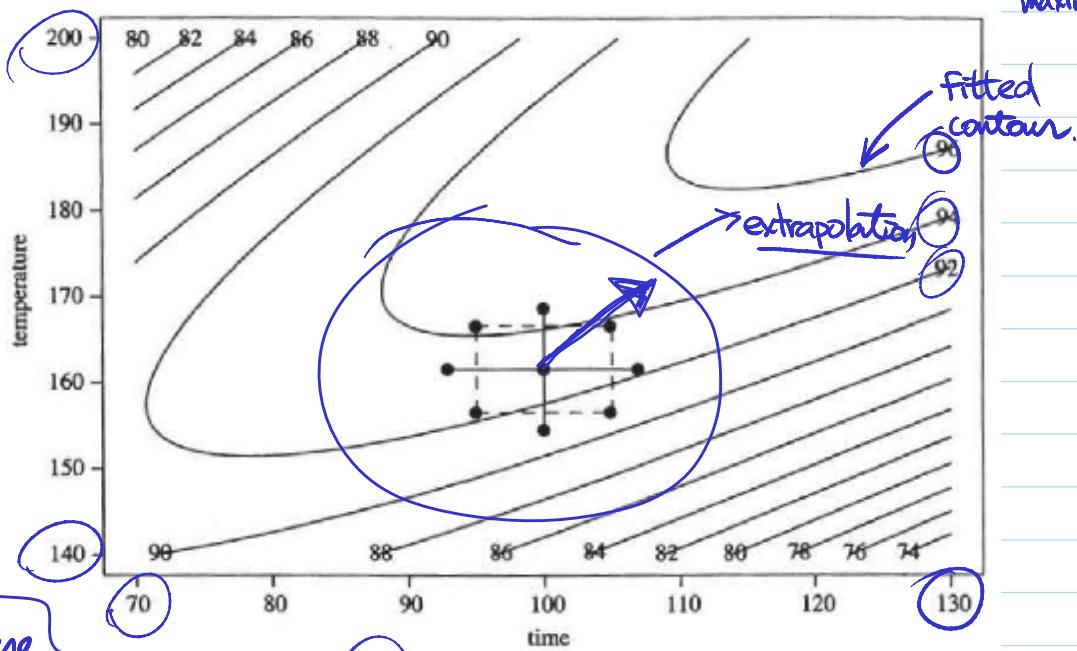
- The results in Table 6 indicate that
 - there are significant interaction and curvature effects
 - the first-order design should be augmented to a **second-order design**
- The axial points of a CCD (runs 7-10 in Table 5) are performed
- The results of fitting a second-order model is given in Table 7. Fitted response surface model:

$$\hat{y} = 93.05 - 0.87x_1 + 2.36x_2 + 0.99x_1x_2 - 0.43x_1^2 - 0.65x_2^2.$$

- The **contours** of the fitted response surface are displayed in Figure 5. It suggests that moving in northeast direction would increase the yield.

*CP. direction is correct but location of maximum is faulty
extrapolation*

Illustrated Second-Order Experiment X



Q: If use different coding for effects, same conclusion?

C.F. \rightarrow Figure 4 (LN p.3-20)

Figure 5: Fitted response surface

✓ Reading: textbook, 10.3.2