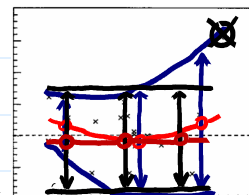
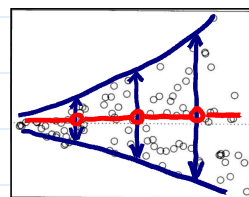


- unfortunately, in real data set, it's rare the pattern is so clear (Q: what will you conclude from the residual plot on the right?)
- in models with many terms or models with complex non-linear mean structure, cannot necessarily associate shapes in a residual plot with a particular problem with the assumptions, e.g.,



(LNp.7-2) true model:  $E(Y) = |x_1|/[2+(1.5+x_2)^2]$  with constant variance  
 fitted model:  $E(Y) = \beta_0 + \beta_1 x_1 + \beta_2 x_2$  → approximate



**nonlinear mean structure**

- possible remedies for unsatisfactory residual plots

| unsatisfactory residual plot | plot residuals against ...                 |  |                           |
|------------------------------|--|--|---------------------------|
|                              | $\hat{y}$                                  | $x_k$  | time order                |
| non-constant variance        | 1. weighted least square<br>2. transform y | 1. weighted least square<br>2. transform y   | weighted least square     |
| curvature in mean structure  | 1. add extra term<br>2. transform y        | 1. add extra term of $x_k$<br>2. transform y | add term of time in model |

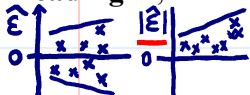
**different philosophy**

❖ Reading: F, 4.1.1

❖ Further reading: D&S, 2.5

→ change current model

11/24

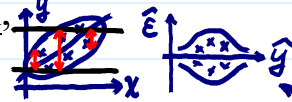


① (LNp.2) → **Non-constant variance** → overall pattern

- if not sure, plot absolute values of residuals against  $\hat{y}$ ,  $x_k$ 's, time order
- when non-constant variance exists,  $\hat{\beta}_{OLS}$  will be more variable than the best estimates ( $\hat{\beta}_{OLS}$  unbiased but not BLUE) and  $\hat{\sigma}$  wrong (⇒ test and C.I. inaccurate)

$\hat{\beta}_{WLS}, \hat{\beta}_{GLS}$

- It's better try to understand the cause of non-constant variance before taking any remedies, e.g., (1) larger response have more "room" to vary, (2) response constrained to lie between a maximum and a minimum, (3) response from Poisson distribution or binomial distribution, ...



⇒ discovering reasons to support the remedies you are going to take

- remedies for non-constant variance
  - ①  $Y_x \sim P(\mu_x), E(Y_x) = \mu_x, Var(Y_x) = \mu_x \rightarrow \sigma_x^2 \propto \mu_x$
  - ②  $Y_x \sim Bin(n, p_x), E(Y_x) = np_x, Var(Y_x) = np_x(1-p_x)$

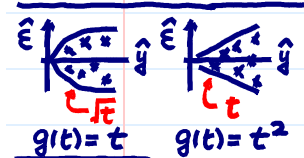
- weighted least squares
  - need weighting information (may from plotting residual vs.  $x_k$ ) or
  - model the form of  $\Sigma$  and using IRWLS → check LNp 6-5

transform  $Y$  (may use information from plotting residual vs.  $\hat{y}$ ) → idea: find a transformation  $h$  such that  $var(h(y_x))$  is a constant, (Q: how? Hint:  $\delta$ -method)

**variance stabilizing transformation**

$Y = XB + \epsilon$   
 $R(Y) = XB' + \epsilon'$

$h(y_x) = h(E(y)) + (y - E(y))h'(E(y))$  → Taylor expansion  
 hope  $var(h(y))$  to be a constant  $c \Rightarrow h'(E(y_x)) \propto 1/(var(y_x))^{1/2}$   
 $h(E(y)) \equiv \int 1/(var(y))^{1/2} d(E(y)) = \int \frac{1}{\sqrt{g(\mu_x)}} d\mu_x \propto \int \frac{1}{\sqrt{g(\mu_x)}} d\mu_x$



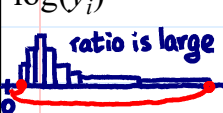
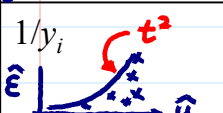
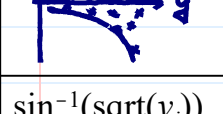
- Example 1:  $var(y_x) \propto [E(y_x)]^2 \Rightarrow$  suggest  $h(y) = \log(y)$   $R(t) = \int \frac{1}{\sqrt{t^2}} dt = \ln(t)$
- Example 2:  $var(y_x) \propto E(y_x) \Rightarrow$  suggest  $h(y) = y^{1/2}$   $R(t) = \int \frac{1}{\sqrt{t}} dt \propto t^{1/2}$

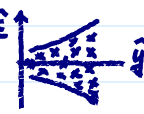
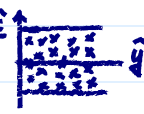
Note: in residual plot, tend to see  $[var(y_x)]^{1/2}$  rather than  $var(y_x)$  (example?)

practical problems:

- if  $y_i \leq 0$ , for some  $i$ , square root or log transformations fail  $\Rightarrow$  can do transformation on  $y_i + d$ , where  $d$  is some small amount s.t.  $y_i + d > 0$  for all  $i$
- transformation may make interpretation difficult  $\leftarrow$  interpretation of  $\hat{\beta}'$  (unit = ?) cf. interpretation of  $\hat{\beta}$

example of transformations  $\leftarrow$  Weisberg (2005). Applied Linear Regression, Sec. 8.3.1

|   |   |  |
|---|---|--|
| $\sqrt{y_i}$<br> | $\text{var}(y_i) \propto E(y_i)^2$  | useful for count data from Poisson distribution  |
| $\log(y_i)$<br>  | $\text{var}(y_i) \propto [E(y_i)]^2$<br>$\sigma_z/u_x = \text{a constant}$ (coefficient of variation)                             | very common, good candidate if the range of $Y$ is very broad, say $y_x$ 's value ranges from 10 to $10^5 \cdot 10^6$  |
| $1/y_i$<br>      | $\text{var}(y_i) \propto [E(y_i)]^4$<br>$R(t) = \int \frac{1}{\sqrt{t^4}} dt = \int \frac{1}{t^2} dt \propto t^{-1}$<br>most data | appropriate when responses are "bunched" near zero, but, in markedly decreasing numbers, large responses do occur<br>heavy-tailed dist. $\leftarrow$ most very few |
| $\sin^{-1}(\sqrt{y_i})$   | $\text{var}(y_i) \propto E(y_i)(1-E(y_i))$<br>$R(t) = \int \frac{1}{\sqrt{t(1-t)}} dt$<br>very few data                           | for binomial proportions   |

- do nothing  $\Rightarrow$  because (i)  $\hat{\beta}_{OLS}$  is still unbiased, although not BLUE; (ii) tests and C.I. inaccurate, but bootstrap may be used to get more accurate results
- use generalized linear model (e.g., Poisson/binomial  $y \Rightarrow \text{var}(y_x)$ : function of  $E(y_x)$ )
- formal test for non-constant variance  $\leftarrow$  OR  $\hat{\sigma}^2$ 
  - regressing absolute residuals on  $\hat{y}$  or  $x_k$ 's
    - 
    - 

- data with replication  $\Rightarrow$  can estimate variances of distinct  $x_i$ 's and test their homogeneity (see D&S, 2.2)

$H_0: \sigma_{x_1}^2 = \sigma_{x_2}^2 = \dots = \sigma_{x_k}^2 \leftarrow$  Bartlett's test

- data without replication  $\Rightarrow$  assign variance a model, test whether parameters in the model equal zero (see Weinberg (2005), 8.3.2)
  - e.g.  $\sigma_z^2 = \sigma^2 \cdot \exp(\lambda z)$  parameters  $\lambda \neq 0$
- formal test may be good at detecting a particular kind of non-constant variance  $\lambda \neq 0$  (depending on the alternative hypothesis), but always do the residual plots

❖ Reading: Faraway (2005, 1st ed.), 4.1.1      ❖ Further reading: D&S, 2.2, 13.6

② (LNp.2) **Curvature in the mean of residuals**

overall pattern

test  $H_0$  vs.  $H_1$   
 $H_0 \cup H_1 =$  all possible models

- related to the concept of lack-of-fit (tests for lack-of-fit can be used if possible), i.e., the current model,  $E(Y) = X\beta$ , may need to be modified for achieving better fitting

Weisberg (2005), Sec. 8.2  $\leftarrow$  too simple

A simple test for curvature: test whether a plot of residuals versus a quantity  $U$  (e.g.,  $\hat{y}$  or  $x_k$ 's) is a null plot or has curvature  $\leftarrow$  can be any reasonable known function of  $U$

- $\Rightarrow$  refit the original mean structure with an additional term  $U^2$  added
- $\Rightarrow$  significant  $t$ -test for  $U^2$  suggests curvature (be aware of collinearity between  $U^2$  and other terms in original mean structure)

- Q: how to identify why the non-linearity happened?
  - plot residuals against  $\hat{y} \Rightarrow$  can tell you whether some problems exist, but cannot tell you why

high  $\text{cor}(x, x^2) \rightarrow$  can use orthogonal polynomial to remove collinearity (future lecture)

plot residuals against  $x_k$ 's or  $y$  against  $x_k$ 's  $\Rightarrow$  may tell you why this problem happened, but in multivariate regression there may exist correlation between predictors, then it's difficult to find why  $x_i$  already appears into model matrix  $X$ . e.g.  $cor(x_k, x_i) \approx 1$ . Then,  $\hat{\epsilon} \perp x_i$  and  $cor(\hat{\epsilon}, x_k) \approx 0$ .

added variable (partial regression) plots

Fitted model:  
 $Y = X_1\beta_1 + \epsilon$

recall:

- regress  $Y$  on all predictors except  $x_k \Rightarrow$  get residuals  $\hat{\epsilon}_Y(x_k)$
- regress  $x_k$  on all predictors except  $x_k \Rightarrow$  get residuals  $\hat{\epsilon}_{x_k}$

$$\hat{\epsilon}_Y(x_k) = \beta_2 \hat{\epsilon}_{x_k} + \epsilon$$

Then,  $\hat{\epsilon} \perp x_i$  and  $cor(\hat{\epsilon}, x_k) \approx 0$

remove collinearity btw  $x_k$  & the other predictors

- $\hat{\epsilon}_Y(x_k)$ : part of  $Y$  not explained by all predictors except  $x_k$
- $\hat{\epsilon}_{x_k}$ : part of  $x_k$  not explained by all predictors except  $x_k$

3. plot  $\hat{\epsilon}_Y(x_k)$  versus  $\hat{\epsilon}_{x_k}$ . Fit simple linear regression:  $\hat{\epsilon}_Y(x_k) = \beta_0 + \beta_k \hat{\epsilon}_{x_k} + \epsilon$

- the slope of a fitted line to the added variable plot is  $\hat{\beta}_k$  and intercept=0 (the line passes (0, 0))

the estimated coefficient of  $x_k$  when  $x_k$  is included in model matrix

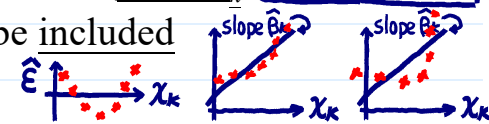
$$\begin{aligned} \because \sum \hat{\epsilon}_Y(x_k) &= 0 \\ \sum \hat{\epsilon}_{x_k} &= 0 \\ \text{if } X_1 &\text{ contains the intercept} \end{aligned}$$

Fitted model:  
 $Y = X_1\beta_1 + X_2\beta_2 + \epsilon$

- a strong relationship between the plotted quantities corresponds to a strong adjusted relationship between  $y$  and  $x_k$
- can be used to check if new predictors should be included

partial residual plots

fitted linear line (Note:  $\hat{\epsilon} \perp x_k$ ): slope  $\hat{\beta}_k$ , pass  $(\bar{x}_k, \hat{\beta}_k \bar{x}_k)$



- plot  $\hat{\epsilon} + \hat{\beta}_k x_k$  versus  $x_k \Rightarrow$  same interpretation as added variable plots

$$y - \sum_{j \neq k} \hat{\beta}_j x_j = \hat{y} + \hat{\epsilon} - \sum_{j \neq k} \hat{\beta}_j x_j = \hat{\epsilon} + \hat{\beta}_k x_k$$

can use Lowess (future lecture) to find how  $x_k$  affect  $y$

remedies for curvature  $\Rightarrow$  adjust the mean structure,  $E(Y) = X\beta$ , for better fitting

many many modeling techniques in addition to linear regression can be adopted (GLM, additive model, nonparametric regression, ACE, AVAS, regression trees, regression spline, MARS)

link function

multivariate adaptive regression spline

alternating conditional expectation

additivity & variance stabilization

Hastie & Tibshirani (1990). Generalized additive models

add more (polynomial or cross product) terms

interaction

- may identify required terms from residual plot, added variable plot, or partial residual plot (polynomial model will be introduced in further lecture)

transformation of response or predictors. idea behind the approach:

(i) a statistical model is a local approximation of the underlying system

(ii) when the mean structure of the underlying system is non-linear and complex, a linear approximation over a relatively wide range of  $X$  may be inadequate (e.g.,  $E[\log(Y)]$ )

Linear model use linear structure  $X\beta$  to approximate the functional relationship between  $y$  &  $x$   
規律

a good fitted model would require a lot of effects (e.g. check LNp 7-9)

$$E(Y) = \beta_0 x_1^{\beta_1} x_2^{\beta_2} \Rightarrow \log(E(Y)) = \log(\beta_0) + \beta_1 \log(x_1) + \beta_2 \log(x_2)$$

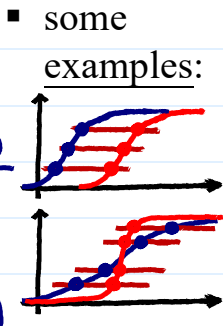
(iii) we sometimes can find suitable transformations of data that will permit a non-linear model to be better approximated (after transformation) by a linear one (e.g., use fewer terms)

CF. variance stabilizing transformation (LNp.10)

$$E(\log(Y)) \approx \log(\beta_0) + \beta_1 \log(x_1) + \beta_2 \log(x_2)$$

a model with only a few terms

$\frac{z_1 - \mu_1}{\sigma_1}$   
 $\sim \frac{z_2 - \mu_2}{\sigma_2}$   
 $\sim N(0, 1)$   
 If  $(z_1, z_2)$   
 such that  
 $\Phi\left(\frac{z_1 - \mu_1}{\sigma_1}\right)$   
 $= \Phi\left(\frac{z_2 - \mu_2}{\sigma_2}\right)$



| transformation |           | non-linear model                         |
|----------------|-----------|--|
| $\log(y)$      | $\log(x)$ | $E(y) = \alpha \prod x_j^{\beta_j}$      |
| $\log(y)$      | $x$       | $E(y) = \alpha \exp(\sum \beta_j x_j)$   |
| $y$            | $\log(x)$ | $E(y) = \alpha + \sum \beta_j \log(x_j)$ |
| $1/y$          | $1/x$     | $E(y) = 1/[\alpha + \sum (\beta_j/x_j)]$ |
| $1/y$          | $x$       | $E(y) = 1/(\alpha + \sum \beta_j x_j)$   |
| $y$            | $1/x$     | $E(y) = \alpha + \sum \beta_j (1/x_j)$   |

some examples:  $\Rightarrow (z_1 - \mu_1)/\sigma_1 = (z_2 - \mu_2)/\sigma_2$   
 There exists numerical method for finding a suitable transformation to improve the fit and/or remedy non-constant variance (e.g., Box-Cox transformation, future lectures)

❖ Reading: F, 4.3, 7.2.4

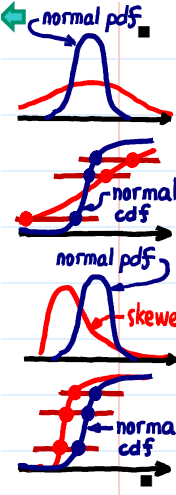
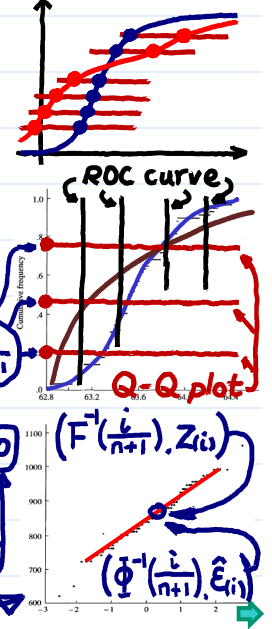
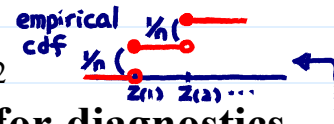
❖ Further reading: D&S, 8.2

### Various plots and tests for diagnostics

quantile vs. quantile

• Q-Q plot

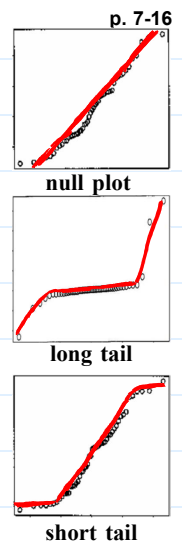
- **Q:** we often see the statement " $z_1, z_2, \dots, z_m$  are i.i.d. from a cdf  $F$ ", how to examine if  $F$  is an appropriate distribution assumption for  $z_j$ 's? (Hint: examine the similarity btw cdf and empirical cdf)
- normal (probability) plot: assessing normality assumption of  $\epsilon$  (Note: tests and C.I. depend on normality assumption)
  1. sort the data  $\hat{\epsilon}_{(1)} \leq \hat{\epsilon}_{(2)} \leq \dots \leq \hat{\epsilon}_{(n)}$ .  $\hat{\epsilon} \sim N(\mu, (1-H)\sigma^2)$  if  $\epsilon \sim N(\mu, \sigma^2 I)$
  2. plot  $\hat{\epsilon}_{(i)}$  against  $\Phi^{-1}(i/(n+1))$ , where  $\Phi$  is the cdf of  $N(0, 1)$ 
    - If the residuals are normally distributed, an approximately straight-line relationship will be observed (null plot)



non-normality: long-tail, short-tail, asymmetric  
 worst case is long-tail; mild non-normality can safely be ignored; the larger the sample size, the less troublesome the non-normality  
 for long-tail, (i) use test based on other distributions, or bootstrap, or permutation tests (ii) for estimation, use robust methods (e.g., least absolute deviation instead of least square)  
 asymmetric, transform  $Y$  (e.g., Box-Cox method)  
 short-tail can be reasonably ignored  
 formal tests exists (such as Kolmogorov-Smirnov test), but not as flexible as the Q-Q plot

tend to generate data with large residuals  $\Rightarrow$  can remove outliers then plot again

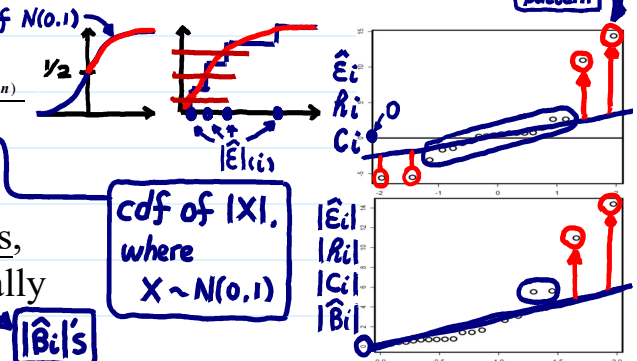
Why? CLT for  $\hat{\beta}$



normal plot can be applied to identify extreme values (e.g., in residuals, leverages, Cook's statistics, ...): in the case, not interested in a straight line relationship, but rather looking for points that depart from the straight line

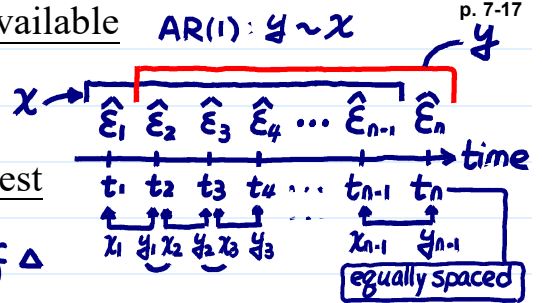
• half-normal plot

- usually used to identify "extreme" values
- can be used to examine residuals, leverages, Cook's statistics, treatment effects (especially for experimental data without replicates)



• diagnostic of correlated errors when a time order is available AR(1):  $y \sim \chi$

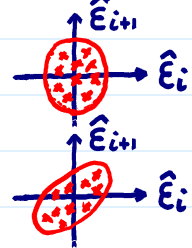
- plot  $\hat{\epsilon}_t$  against time  $lag 2, lag 3, \dots \leftarrow lag 1$
- plot  $\hat{\epsilon}_{i+1}$  against  $\hat{\epsilon}_i$ , when  $i$  related to time
- use formal tests like the Durbin-Watson or runs test



$$\begin{aligned} & \sum (\hat{\epsilon}_i - \hat{\epsilon}_{i-1})^2 \\ &= \sum \hat{\epsilon}_i^2 \\ &+ \sum \hat{\epsilon}_{i-1}^2 \\ &- 2 \sum \hat{\epsilon}_i \hat{\epsilon}_{i-1} \end{aligned}$$

$$DW = \frac{\sum_{i=2}^n (\hat{\epsilon}_i - \hat{\epsilon}_{i-1})^2}{\sum_{i=1}^n \hat{\epsilon}_i^2}$$

Information of  $\Delta$



a correlation matrix of  $\epsilon_i$ 's ( $Y_i$ 's)

|              |              |              |              |              |     |
|--------------|--------------|--------------|--------------|--------------|-----|
|              | $\epsilon_1$ | $\epsilon_2$ | $\epsilon_3$ | $\epsilon_4$ | ... |
| $\epsilon_1$ | 1            | $\Delta$     | $\times$     | $\square$    |     |
| $\epsilon_2$ | $\Delta$     | 1            | $\Delta$     | $\times$     |     |
| $\epsilon_3$ | $\times$     | $\Delta$     | 1            | $\Delta$     |     |
| $\epsilon_4$ | $\square$    | $\times$     | $\Delta$     | 1            |     |
| ...          |              |              |              |              |     |

- $0 \leq DW \leq 4$
- positively correlated  $\Rightarrow DW \rightarrow 0$
- negatively correlated  $\Rightarrow DW \rightarrow 4$
- under null (i.e., correlation=0)  $\Rightarrow DW \approx 2$
- null distribution depends on  $X \leftarrow \because \hat{\epsilon} = (I-H)\epsilon$  and  $\epsilon \sim N(0, \sigma^2 I)$  under null.

➤ use GLS when you have correlated errors

$1 > |\Delta| > |\chi| > |0| > \dots$   
 cor  $\downarrow$  as time duration  $\uparrow$

❖ Reading: F, 4.1.2, 4.1.3

❖ Further reading: D&S, 2.4, 2.7, chapter 7

